Dynamic Programming

Section 12.2



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Matrix Chain-Products (not in book)





Matrix Chain-Products



Matrix Chain-Product:

- Compute $A = A_0 * A_1 * ... * A_{n-1}$
- A_i is $d_i \times d_{i+1}$
- Problem: How to parenthesize?
- Example
 - B is 3 × 100
 - C is 100 × 5
 - D is 5 × 5
 - (B*C)*D takes 1500 + 75 = 1575 ops
 B*(C*D) takes 1500 + 2500 = 4000 ops

An Enumeration Approach

Matrix Chain-Product Alg.:

- Try all possible ways to parenthesize A=A₀*A₁*...*A_{n-1}
- Calculate number of ops for each one
- Pick the one that is best

Running time:

- The number of parenthesizations is equal to the number of binary trees with n nodes
- This is exponential!
- It is called the Catalan number, and it is almost 4ⁿ.
- This is a terrible algorithm!

A Greedy Approach



Idea #1: repeatedly select the product that uses (up) the most operations.

- Counter-example:
 - A is 10 × 5
 - B is 5 × 10
 - C is 10 × 5
 - D is 5 × 10
 - Greedy idea #1 gives (A*B)*(C*D), which takes 500+1000+500 = 2000 ops
 - A*((B*C)*D) takes 500+250+250 = 1000 ops



Another Greedy Approach

- Idea #2: repeatedly select the product that uses the fewest operations.
- Counter-example:
 - A is 101 × 11
 - B is 11 × 9
 - C is 9 × 100
 - D is 100 × 99
 - Greedy idea #2 gives A*((B*C)*D)), which takes 109989+9900+108900=228789 ops
 - (A*B)*(C*D) takes 9999+89991+89100=189090 ops

The greedy approach is not giving us the optimal value.

A "Recursive" Approach

Define subproblems:

- Find the best parenthesization of $A_i * A_{i+1} * ... * A_j$.
- Let N_{i,j} denote the number of operations done by this subproblem.
- The optimal solution for the whole problem is N_{0,n-1}.

Subproblem optimality: The optimal solution can be defined in terms of optimal subproblems

- There has to be a final multiplication (root of the expression tree) for the optimal solution.
- Say, the final multiply is at index i: $(A_0^*...^*A_i)^*(A_{i+1}^*...^*A_{n-1})$.
- Then the optimal solution N_{0,n-1} is the sum of two optimal subproblems, N_{0,i} and N_{i+1,n-1} plus the time for the last multiply.
 - If the global optimum did not have these optimal subproblems, we could define an even better "optimal" solution.

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A Characterizing Equation



- The global optimal has to be defined in terms of optimal subproblems, depending on where the final multiply is at.
- Let us consider all possible places for that final multiply:
 - Recall that A_i is a $d_i \times d_{i+1}$ matrix.
 - So, a characterizing equation for N_{i,j} is the following:

$$N_{i,j} = \min_{i \le k < j} \{N_{i,k} + N_{k+1,j} + d_i d_{k+1} d_{j+1}\}$$

Note that subproblems are not independent--the subproblems overlap.

A Dynamic Programming Algorithm



- Since subproblems overlap, we don't use recursion.
- Instead, we construct optimal subproblems
 "bottom-up."
- N_{i,i}'s are easy, so start with them
- Then do length
 2,3,... subproblems,
 and so on.
- The running time is O(n³)

Algorithm *matrixChain(S)*:

Input: sequence S of n matrices to be multipliedOutput: number of operations in an optimal parenthisization of S

for $i \leftarrow 1$ to n-1 do

 $N_{ii} \leftarrow 0$

for
$$b \leftarrow 1$$
 to *n-1* do

for $i \leftarrow 0$ to *n-b-1* do

 $j \leftarrow i + b$ $N_{i,j} \leftarrow + \text{infinity}$ for $k \leftarrow i$ to j - 1 do

 $N_{i,j} \leftarrow \min\{N_{i,j}, N_{i,k} + N_{k+1,j} + d_i d_{k+1} d_{j+1}\}$

A Dynamic Programming Algorithm Visualization



 $N_{i,j} = \min_{i \le k < j} \{N_{i,k} + N_{k+1,j} + d_i d_{k+1} d_{j+1}\}$ The bottom-up answer n-1 construction fills in the N 0 1 2 N array by diagonals 0 N_{i,i} gets values from previous entries in i-th . . . row and j-th column Filling in each entry in the N table takes O(n) time. Total run time: O(n³) Getting actual n-1 parenthesization can be done by remembering "k" for each N entry

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The General Dynamic Programming Technique



- Applies to a problem that at first seems to require a lot of time (possibly exponential), provided we have:
 - Simple subproblems: the subproblems can be defined in terms of a few variables, such as j, k, l, m, and so on.
 - Subproblem optimality: the global optimum value can be defined in terms of optimal subproblems
 - Subproblem overlap: the subproblems are not independent, but instead they overlap (hence, should be constructed bottom-up).

Subsequences

A subsequence of a character string $x_0x_1x_2...x_{n-1}$ is a string of the form $x_{i_1}x_{i_2}...x_{i_k}$, where $i_j < i_{j+1}$. Not the same as substring! Example String: ABCDEFGHIJK Subsequence: ACEGIJK Subsequence: DFGHK Not subsequence: DAGH

The Longest Common Subsequence (LCS) Problem

- Given two strings X and Y, the longest common subsequence (LCS) problem is to find a longest subsequence common to both X and Y
- Has applications to DNA similarity testing (alphabet is {A,C,G,T})
- Example: ABCDEFG and XZACKDFWGH have ACDFG as a longest common subsequence

A Poor Approach to the LCS Problem

A Brute-force solution:

- Enumerate all subsequences of X
- Test which ones are also subsequences of Y
- Pick the longest one.
- Analysis:
 - If X is of length n, then it has 2ⁿ subsequences
 - This is an exponential-time algorithm!

A Dynamic-Programming Approach to the LCS Problem

- Define L[i,j] to be the length of the longest common subsequence of X[0..i] and Y[0..j].
- Allow for -1 as an index, so L[-1,k] = 0 and L[k,-1]=0, to indicate that the null part of X or Y has no match with the other.
- Then we can define L[i,j] in the general case as follows:
 - 1. If $x_i = y_j$, then L[i,j] = L[i-1,j-1] + 1 (we can add this match)
 - 2. If $x_i \neq y_j$, then L[i,j] = max{L[i-1,j], L[i,j-1]} (we have no match here)



An LCS Algorithm

Algorithm LCS(X,Y):

Input: Strings X and Y with n and m elements, respectively **Output:** For i = 0, ..., n-1, j = 0, ..., m-1, the length L[i, j] of a longest string that is a subsequence of both the string $X[0..i] = x_0 x_1 x_2 ... x_i$ and the string Y [0.. j] = $y_0 y_1 y_2 ... y_i$ for i =1 to n-1 do L[i,-1] = 0**for** j =0 to m-1 **do** L[-1,j] = 0**for** i =0 to n-1 **do for** j =0 to m-1 **do** if $x_i = y_i$ then L[i, j] = L[i-1, j-1] + 1else $L[i, j] = max\{L[i-1, j], L[i, j-1]\}$ return array L

Visualizing the LCS Algorithm

L	-1	0	1	2	3	4	5	6	7	8	9	10	11
-1	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	1	1	1	1	1	1	1	1	1	1	1
1	0	0	1	1	2	2	2	2	2	2	2	2	2
2	0	0	1	1	2	2	2	3	3	3	3	3	3
3	0	1	1	1	2	2	2	3	3	3	3	3	3
4	0	1	1	1	2	2	2	3	3	3	3	3	3
5	0	1	1	1	2	2	2	3	4	4	4	4	4
6	0	1	1	2	2	3	3	3	4	4	5	5	5
7	0	1	1	2	2	3	4	4	4	4	5	5	6
8	0	1	1	2	3	3	4	5	5	5	5	5	6
9	0	1	1	2	3	4	4	5	5	5	6	6	6



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Analysis of LCS Algorithm

We have two nested loops The outer one iterates n times The inner one iterates *m* times A constant amount of work is done inside each iteration of the inner loop Thus, the total running time is O(nm) Answer is contained in L[n,m] (and the subsequence can be recovered from the

L table).