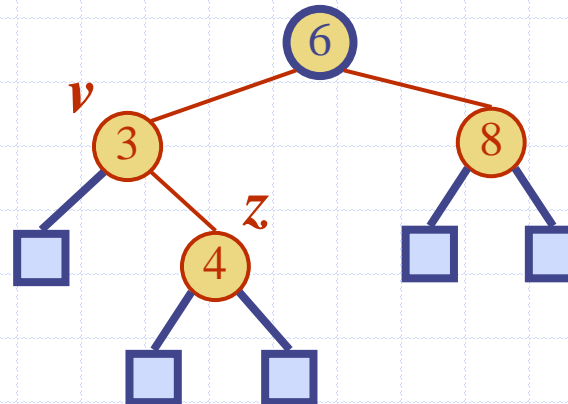


Splay Trees

Section 10.3



Splay Trees

- ◆ **Splay trees** are “balanced” in an amortized sense.
- ◆ They require no extra balance information to be stored.
- ◆ Worst-case operation time is $O(n)$.
- ◆ Amortized worst-case operation time is $O(\log n)$.
- ◆ Good choice when overall performance is more important than per-operation performance.
- ◆ Good choice when some elements are accessed more frequently than others.

Splay Trees are Binary Search Trees

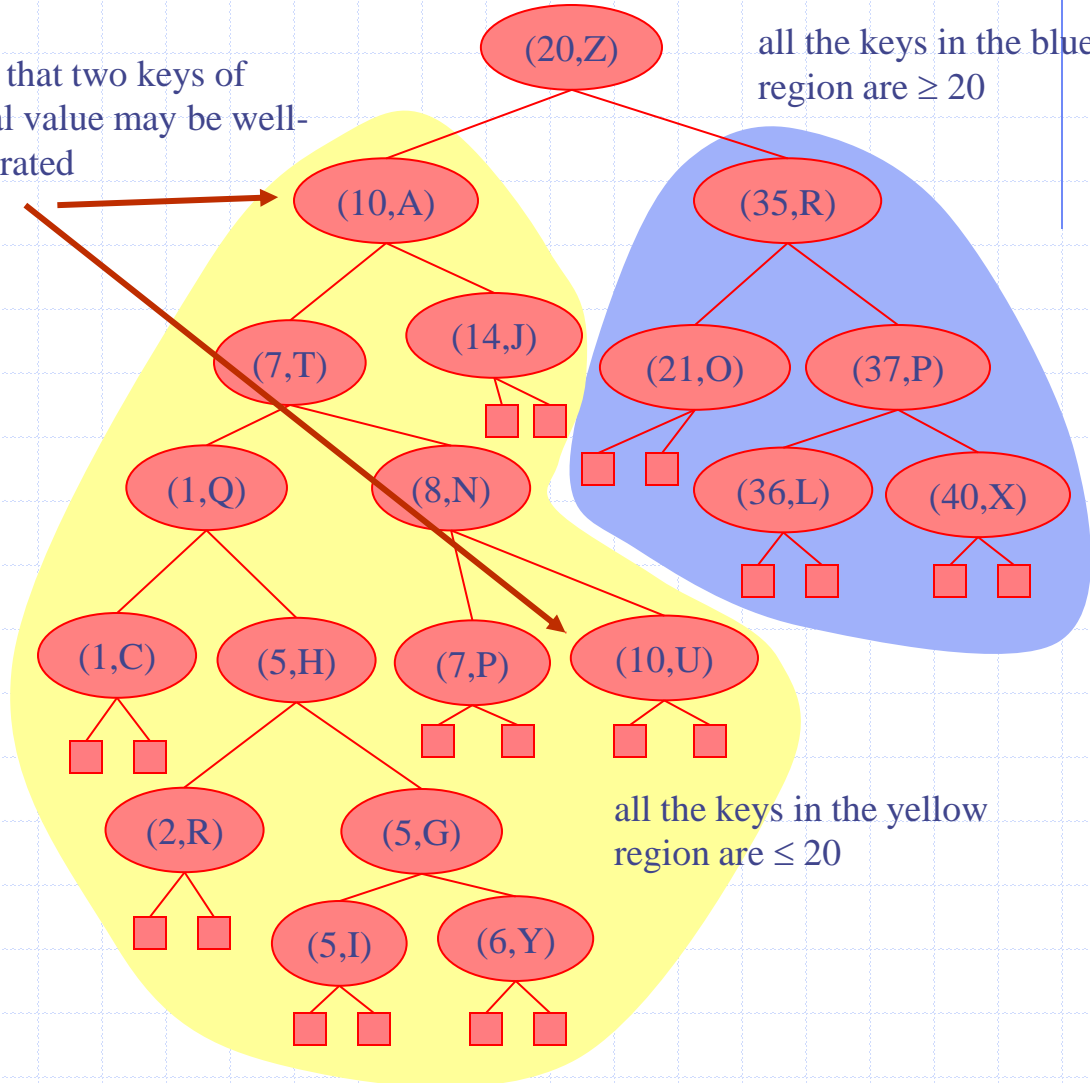
◆ BST Rules:

- entries stored only at internal nodes
- keys stored at nodes in the left subtree of v are less than or equal to the key stored at v
- keys stored at nodes in the right subtree of v are greater than or equal to the key stored at v

◆ An inorder traversal will return the keys in order

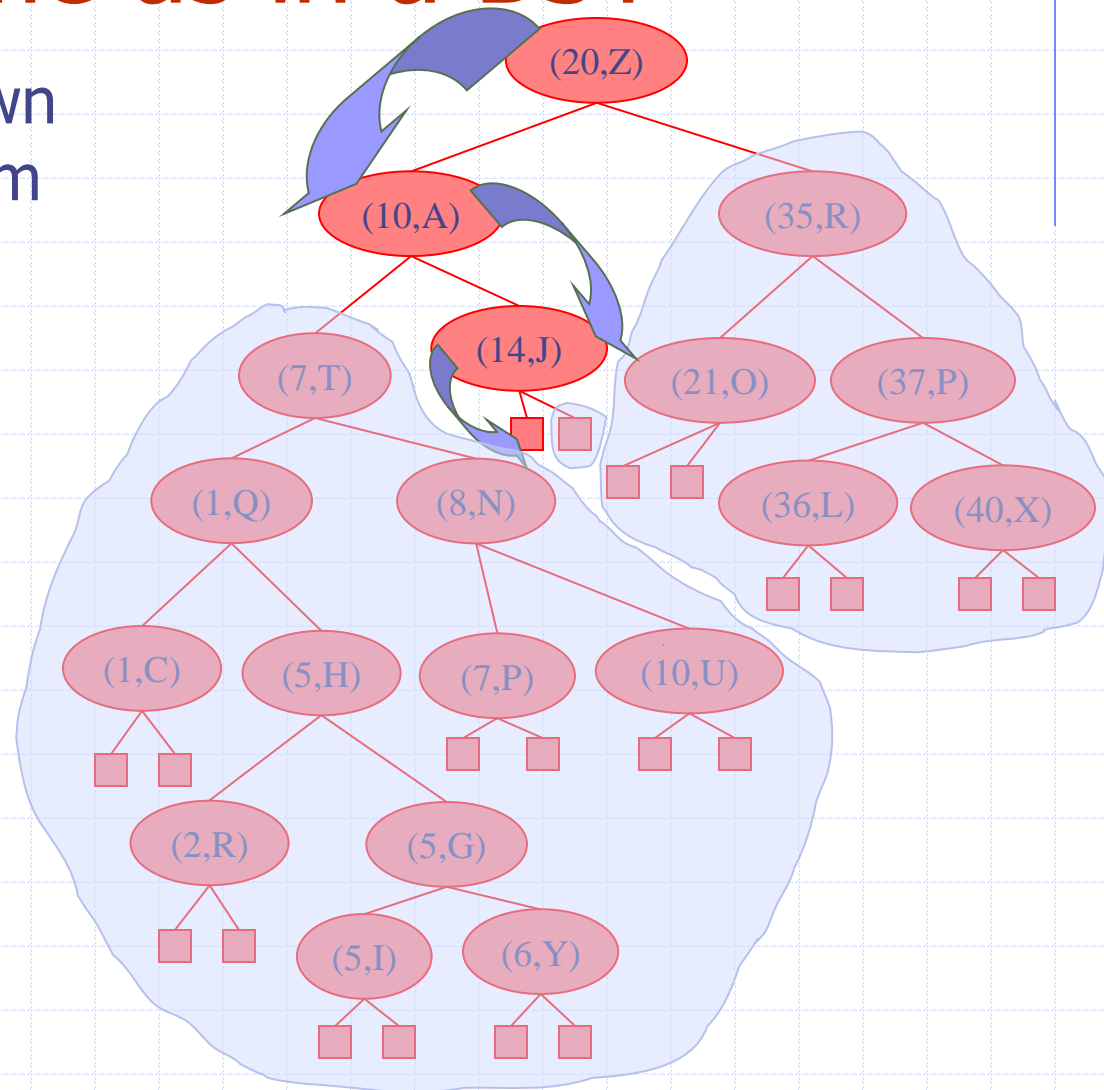
note that two keys of equal value may be well-separated

all the keys in the blue region are ≥ 20



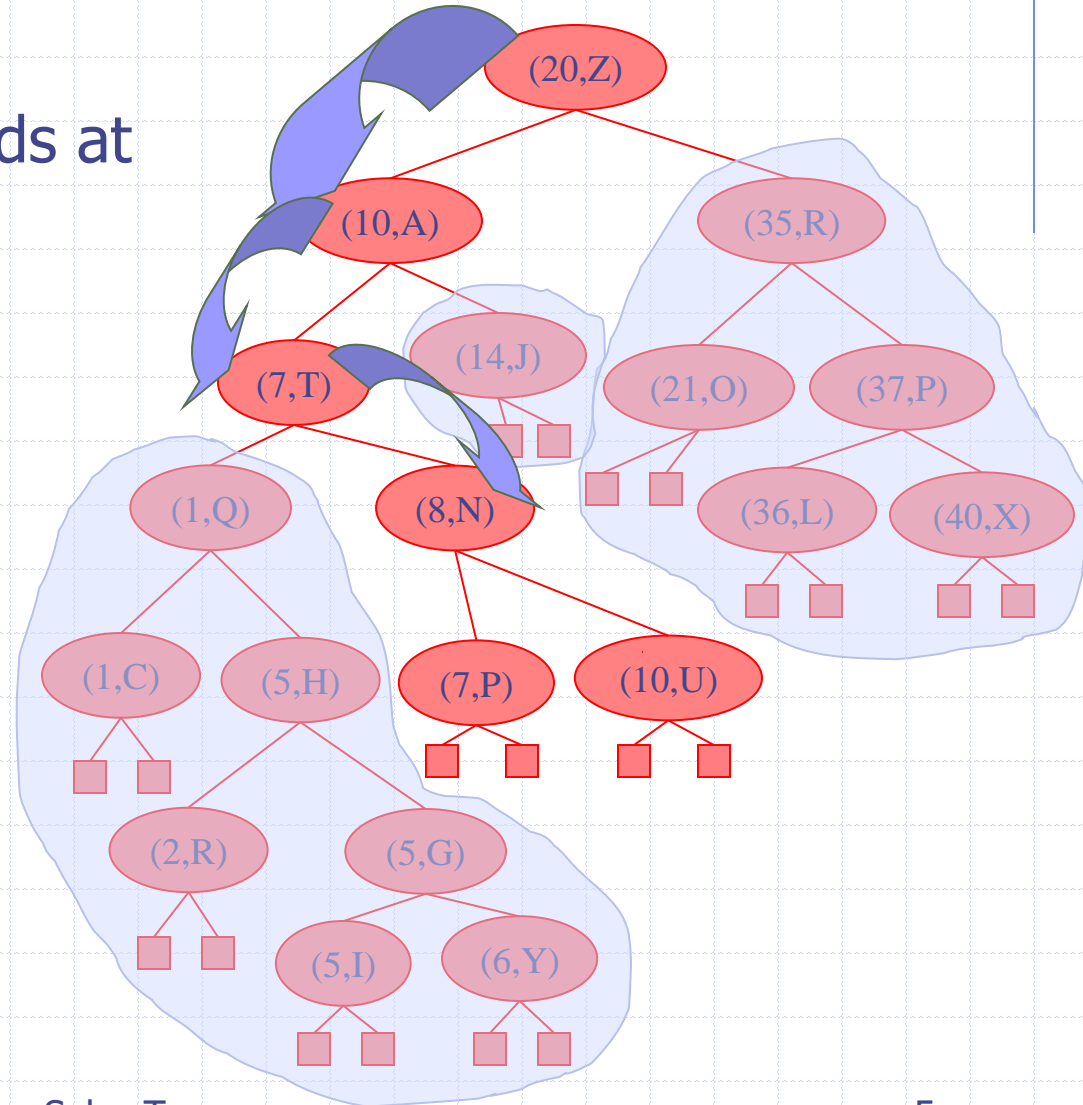
Searching in a Splay Tree: Starts the Same as in a BST

- ◆ Search proceeds down the tree to find item or an external node.
- ◆ Example: Search for node with key 11.



Example Searching in a BST, continued

- ◆ search for key 8, ends at an internal node.



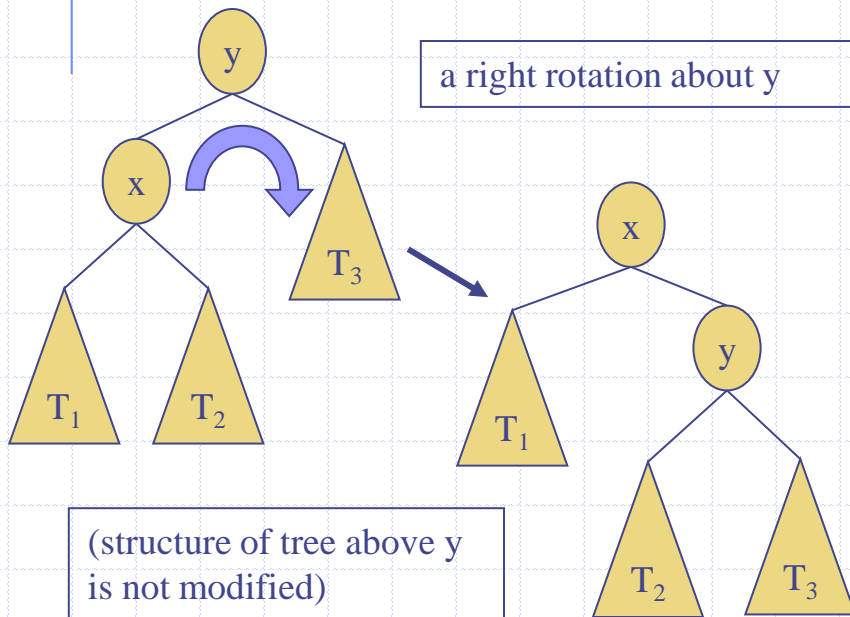
Splay Trees do Rotations after Every Operation (Even Search)

◆ new operation: *splay*

- splaying moves a node to the root using rotations

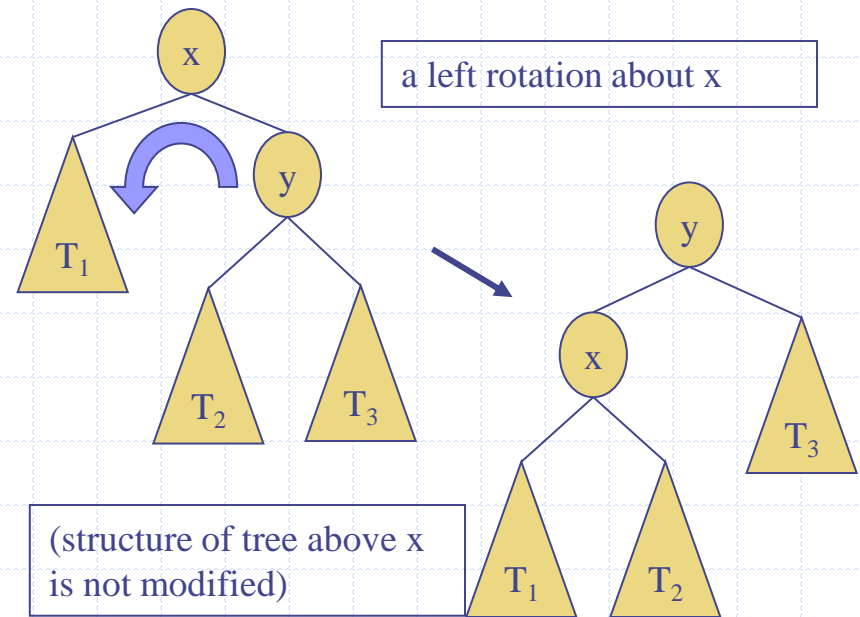
■ right rotation

- makes the left child x of a node y into y 's parent; y becomes the right child of x



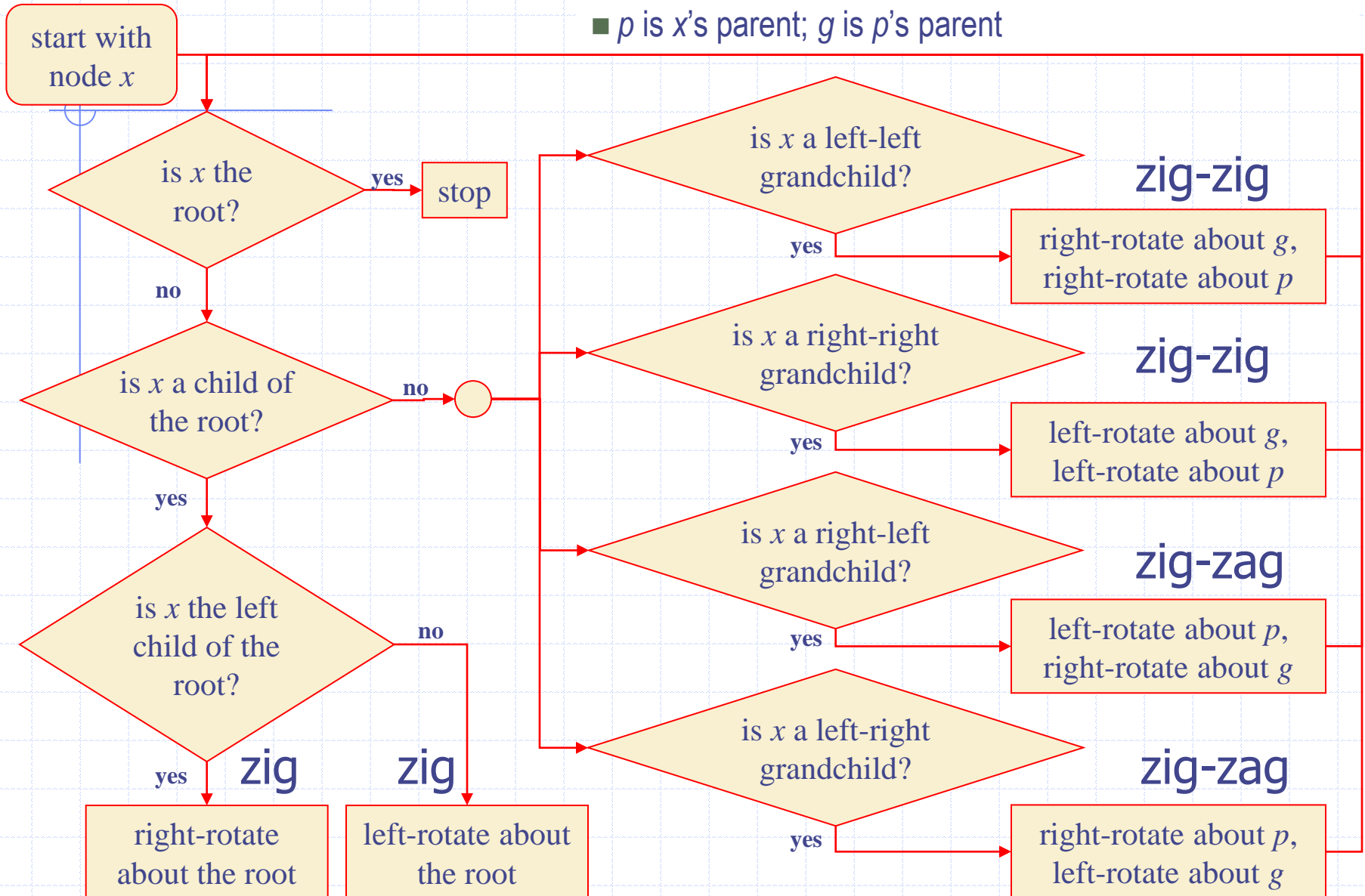
■ left rotation

- makes the right child y of a node x into x 's parent; x becomes the left child of y

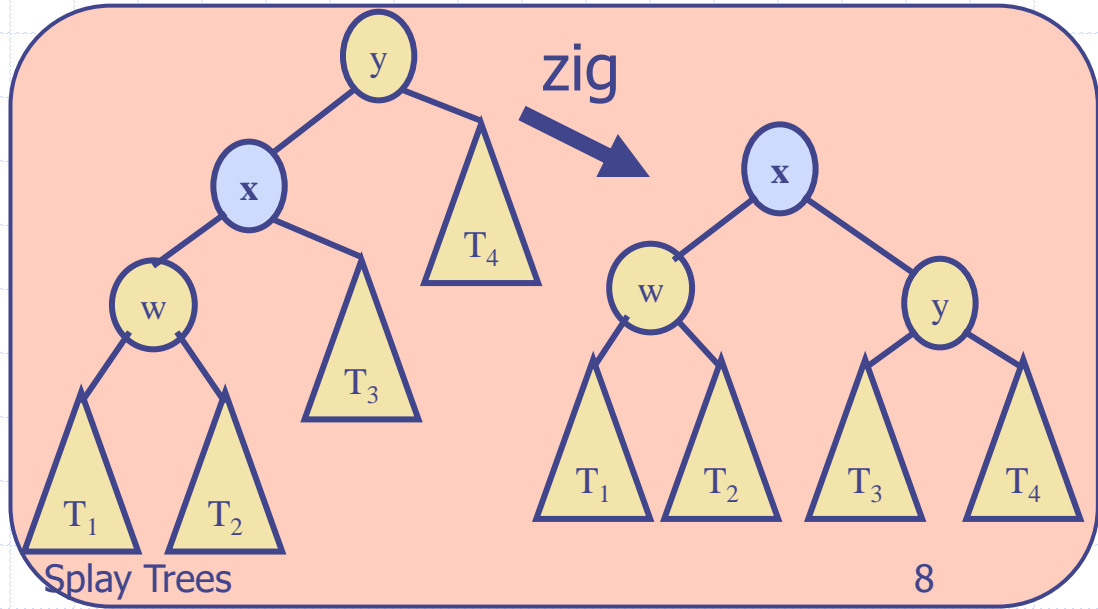
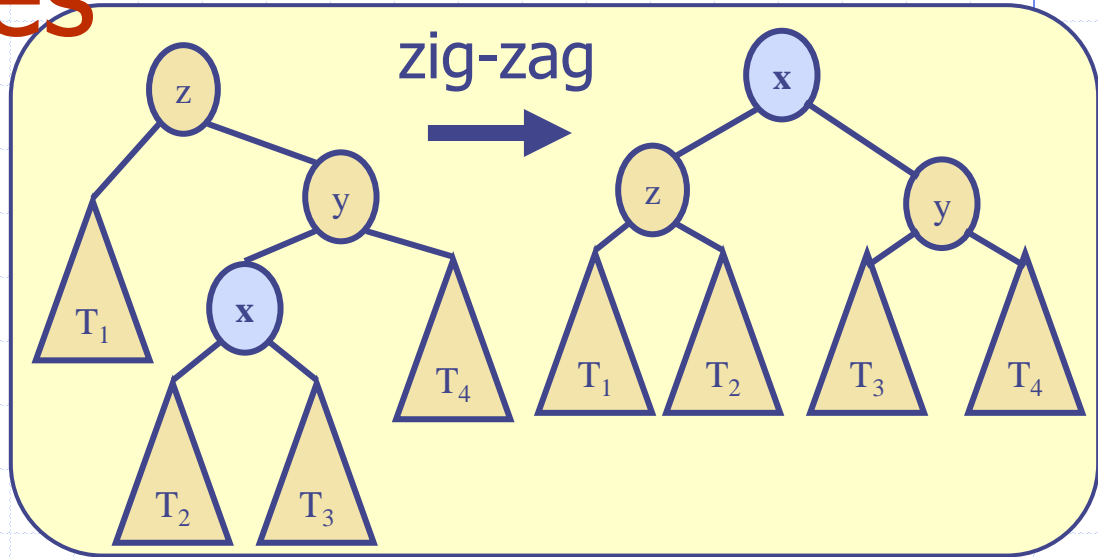
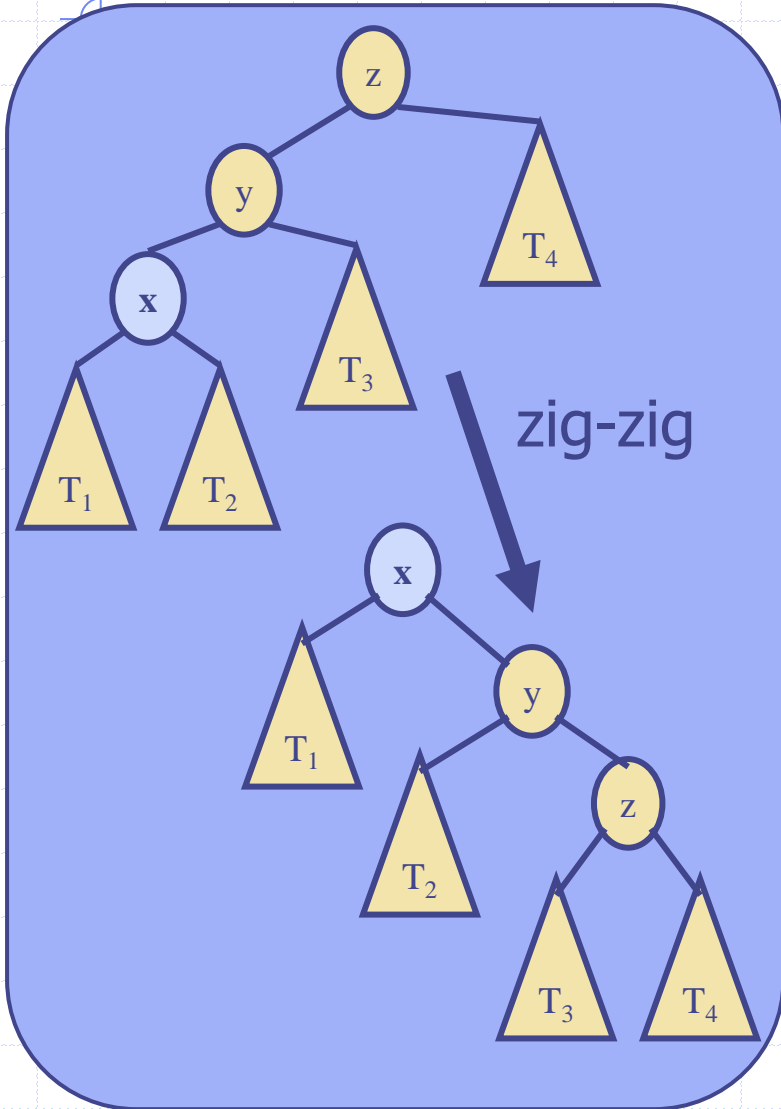


Splaying:

- “ x is a left-left grandchild” means x is a left child of its parent, which is itself a left child of its parent
- p is x 's parent; g is p 's parent



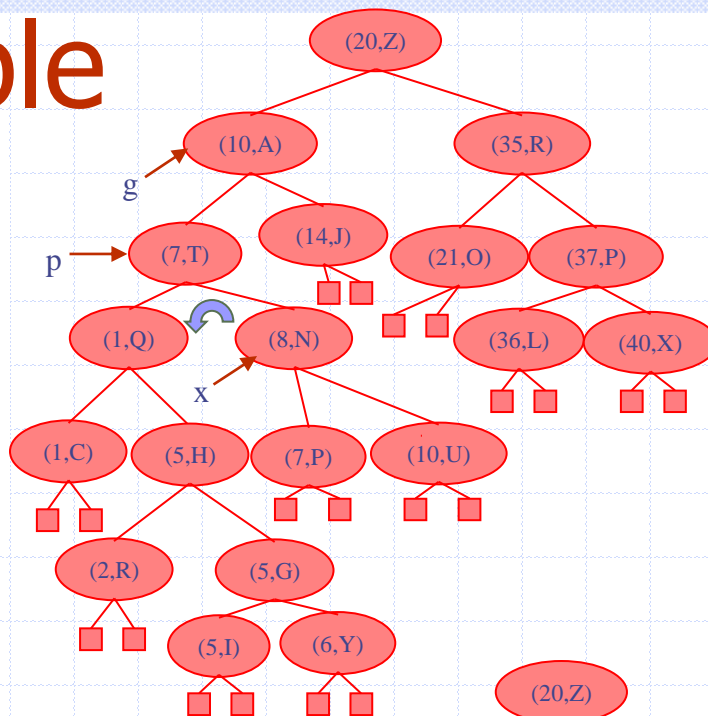
Visualizing the Splaying Cases



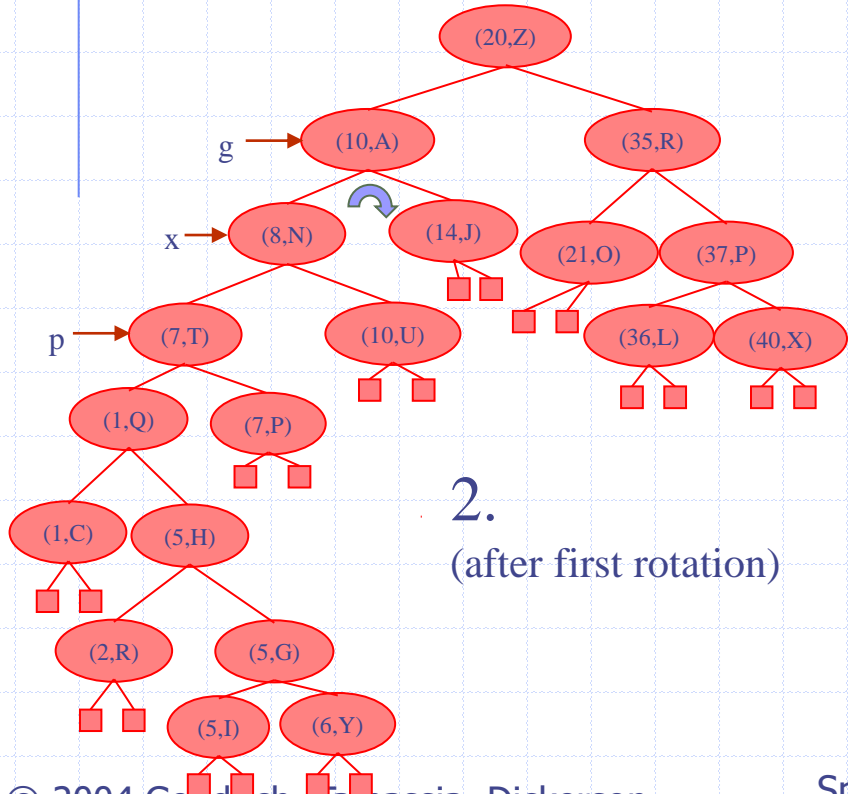
Splaying Example

◆ let $x = (8,N)$

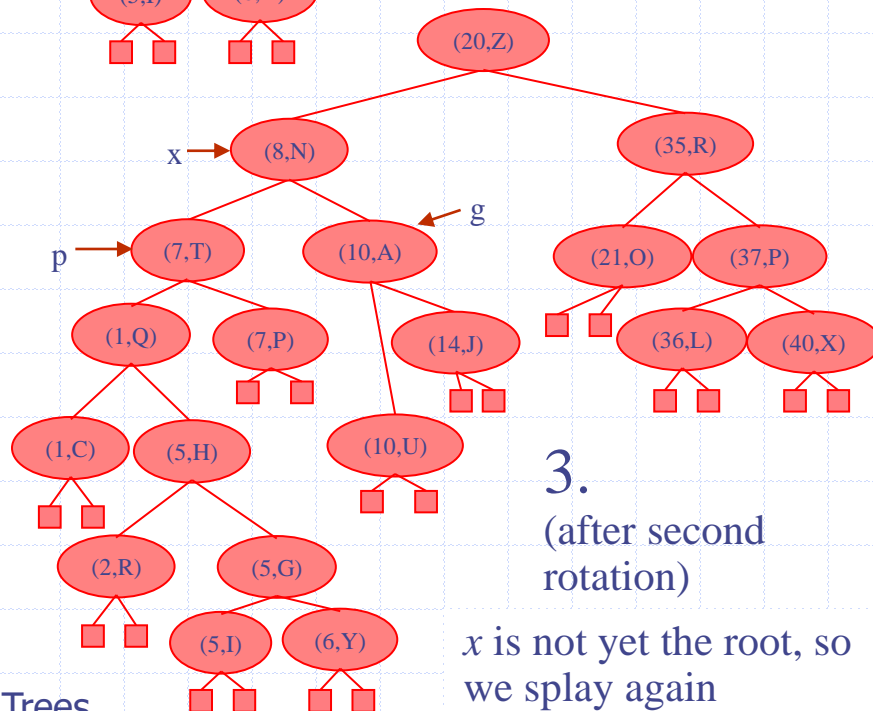
- x is the right child of its parent, which is the left child of the grandparent
- left-rotate around p , then right-rotate around g



1.
(before rotating)



2.
(after first rotation)

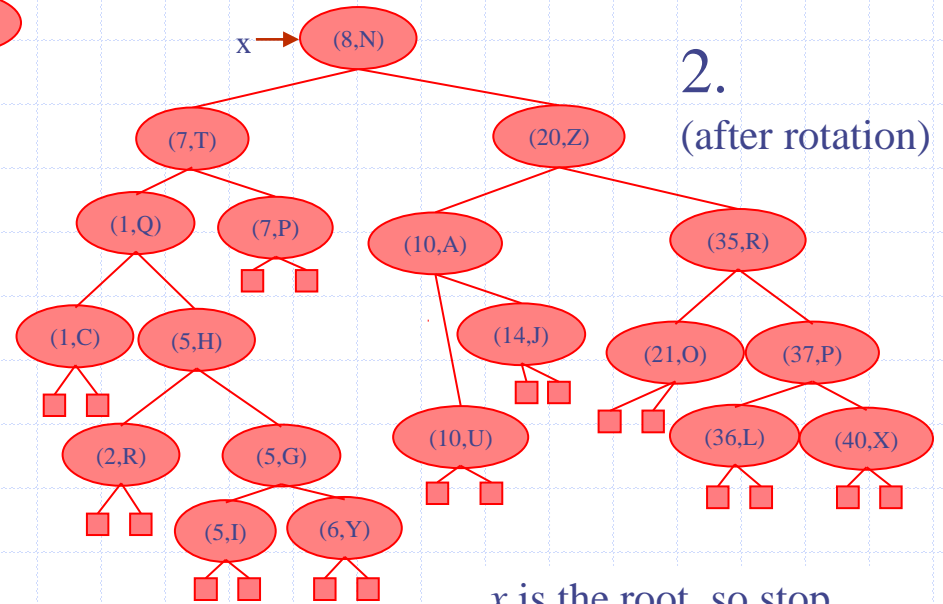
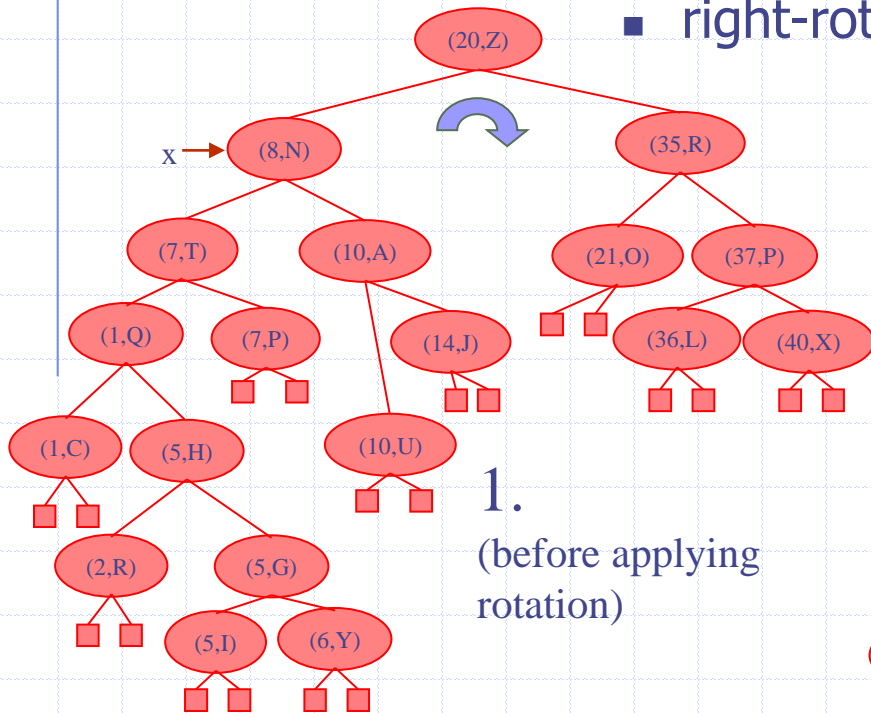


3.
(after second rotation)

x is not yet the root, so we splay again

Splaying Example, Continued

- ◆ now x is the left child of the root
 - right-rotate around root

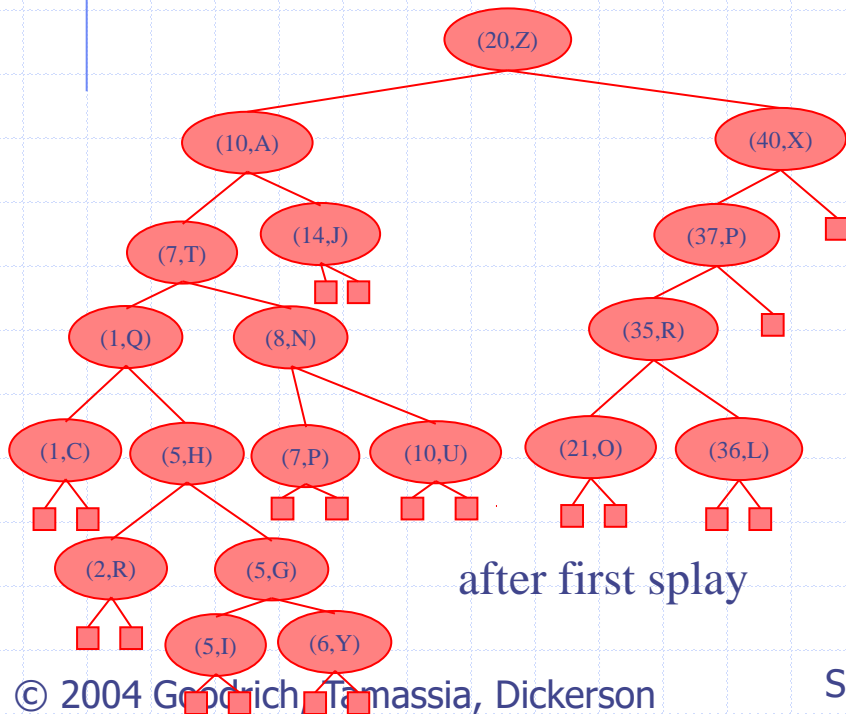
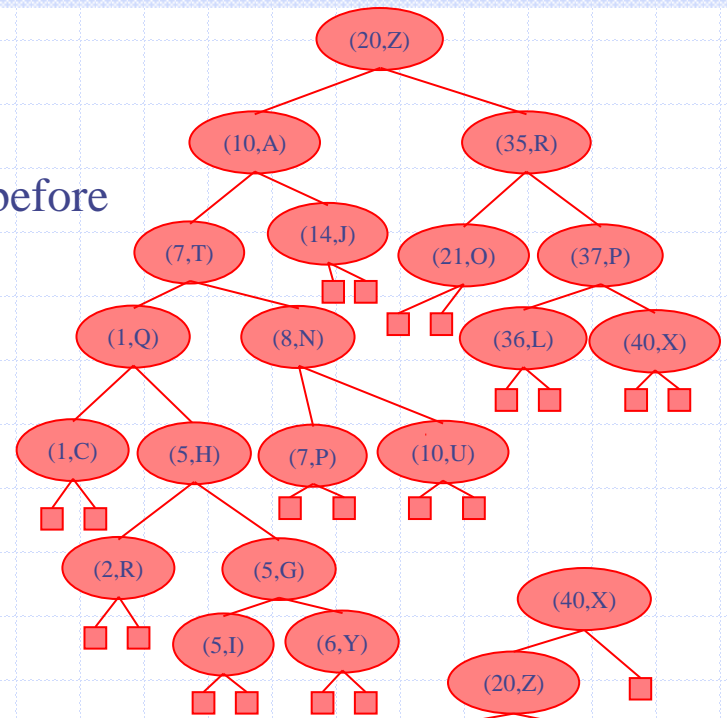


x is the root, so stop

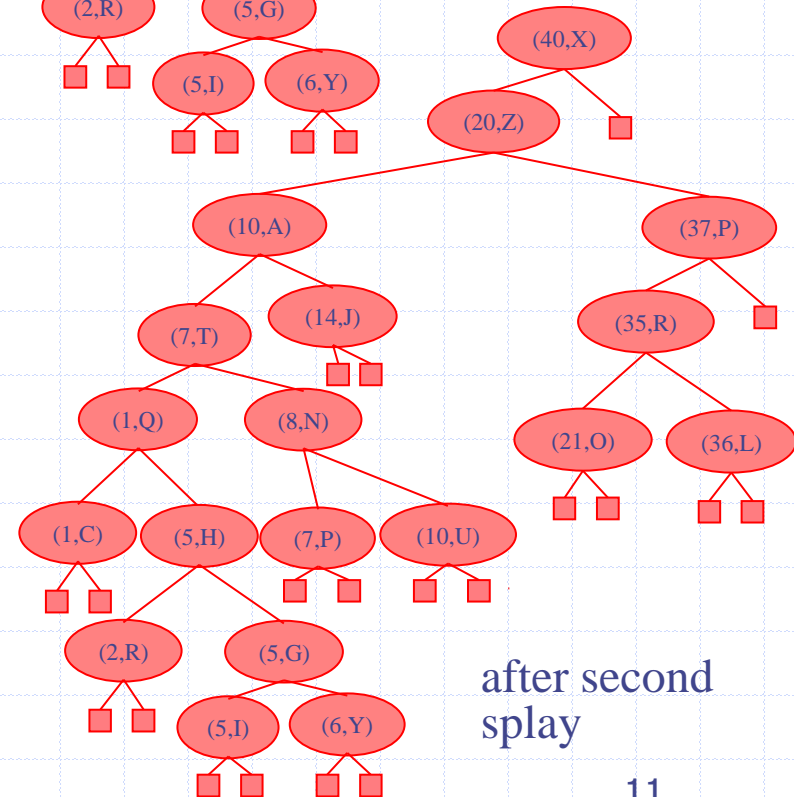
Example Result of Splaying

- ◆ tree might not be more balanced
- ◆ e.g. splay (40,X)
 - before, the depth of the shallowest leaf is 3 and the deepest is 7
 - after, the depth of shallowest leaf is 1 and deepest is 8

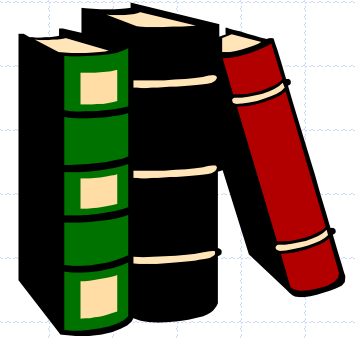
before



after first splay



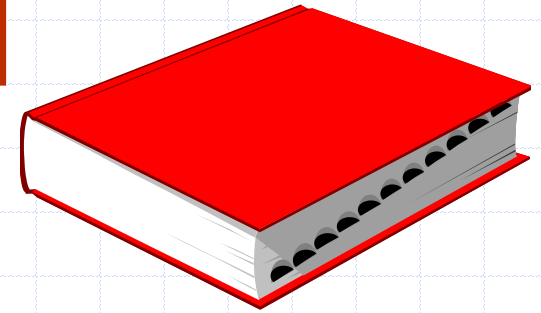
after second splay



Splay Tree Definition

- ◆ a **splay tree** is a binary search tree where a node is splayed after it is accessed (for a search or update)
 - deepest internal node accessed is splayed
 - splaying costs $O(h)$, where h is height of the tree
 - which is still $O(n)$ worst-case
 - ◆ $O(h)$ rotations, each of which is $O(1)$

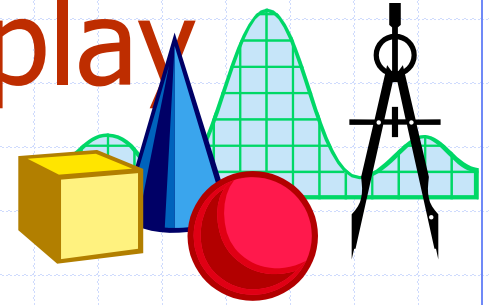
Splay Trees & Ordered Dictionaries



- ◆ which nodes are splayed after each operation?

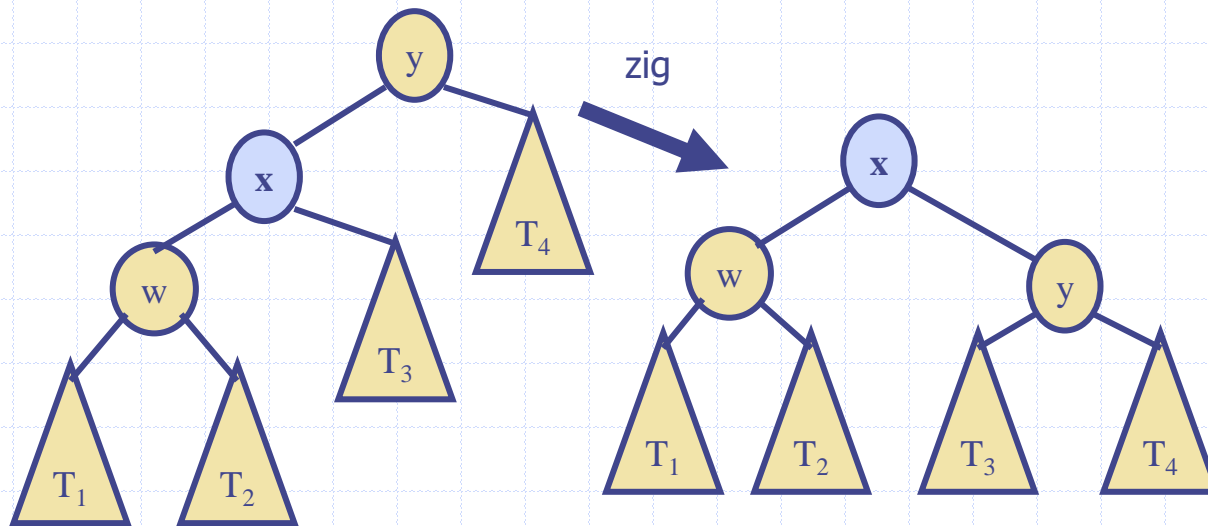
method	splay node
get(k)	if key found, use that node if key not found, use parent of ending external node
put(k,v)	use the new node containing the entry inserted
erase(k)	use the parent of the internal node that was actually removed from the tree (the parent of the node that the removed item was swapped with)

Amortized Analysis of Splay Trees



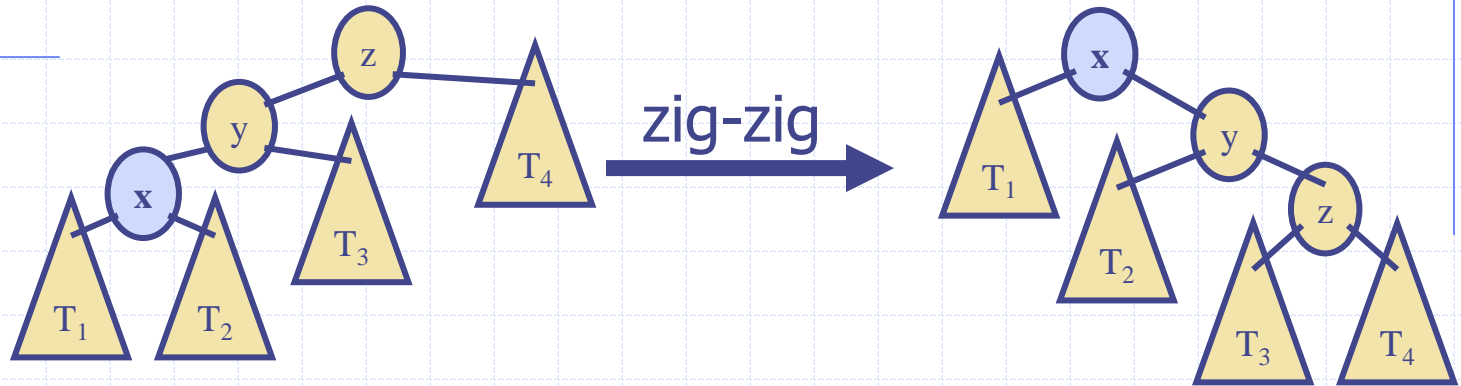
- ◆ We use the **accounting method** of amortized analysis.
- ◆ Running time of each operation is proportional to time for splaying.
- ◆ Define $\text{rank}(v)$ as the logarithm (base 2) of the number of nodes in subtree rooted at v .
- ◆ Time costs: zig = \$1, zig-zig = \$2, zig-zag = \$2.
- ◆ Thus, time cost for splaying a node at depth $d = \$d$.
- ◆ Imagine that we store $\text{rank}(v)$ cyber-dollars at each node v of the splay tree (just for the sake of analysis).

Cyber-dollar Cost per Zig

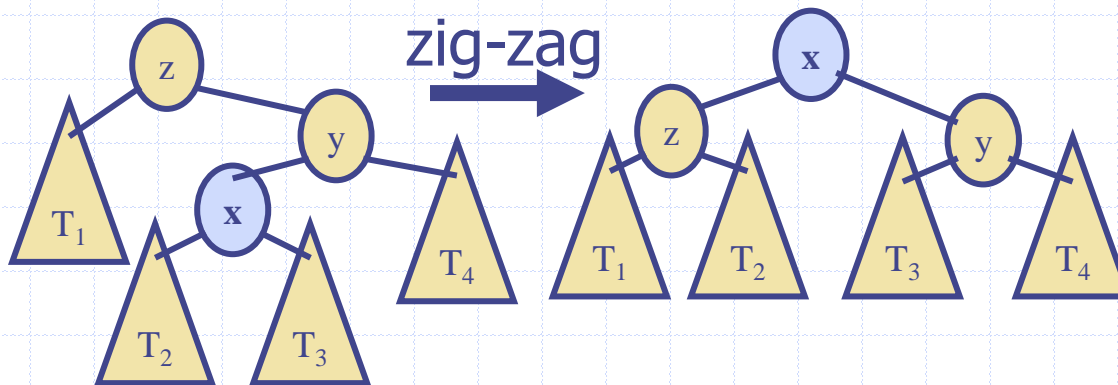


- ◆ Doing a zig at x costs at most $\text{rank}'(x) - \text{rank}(x)$:
 - $\text{cost} = \underline{\text{rank}'(x)} + \text{rank}'(y) - \underline{\text{rank}(y)} - \text{rank}(x)$
 $= \text{rank}'(y) - \text{rank}(x)$
 $\leq \text{rank}'(x) - \text{rank}(x).$

Cost per zig-zig and zig-zag



- ◆ Doing a zig-zig or zig-zag at x costs at most $3(\text{rank}'(x) - \text{rank}(x)) - 2$





Cost of Splaying

◆ Cost of splaying a node x at depth d of a tree rooted at r :

- at most $3(\text{rank}(r) - \text{rank}(x)) - d + 2$:
- Proof: Splaying x takes $d/2$ splaying substeps:

$$\begin{aligned}\text{cost} &\leq \sum_{i=1}^{d/2} \text{cost}_i \\ &\leq \sum_{i=1}^{d/2} (3(\text{rank}_i(x) - \text{rank}_{i-1}(x)) - 2) + 2 \\ &= 3(\text{rank}(r) - \text{rank}_0(x)) - 2(d/2) + 2 \\ &\leq 3(\text{rank}(r) - \text{rank}(x)) - d + 2.\end{aligned}$$

Performance of Splay Trees



- ◆ Recall: rank of a node is logarithm of its size.
- ◆ Thus, amortized cost of any splay operation is $O(\log n)$
- ◆ In fact, the analysis goes through for any reasonable definition of $\text{rank}(x)$
- ◆ This implies that splay trees can actually adapt to perform searches on frequently-requested items much faster than $O(\log n)$ in some cases

Red-Black Trees

Section 10.5

