

ENSC327

Communications Systems

**26: Intro and overview of Baseband
Pulse Amplitude Modulation(PAM)**



School of Engineering Science

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Outline

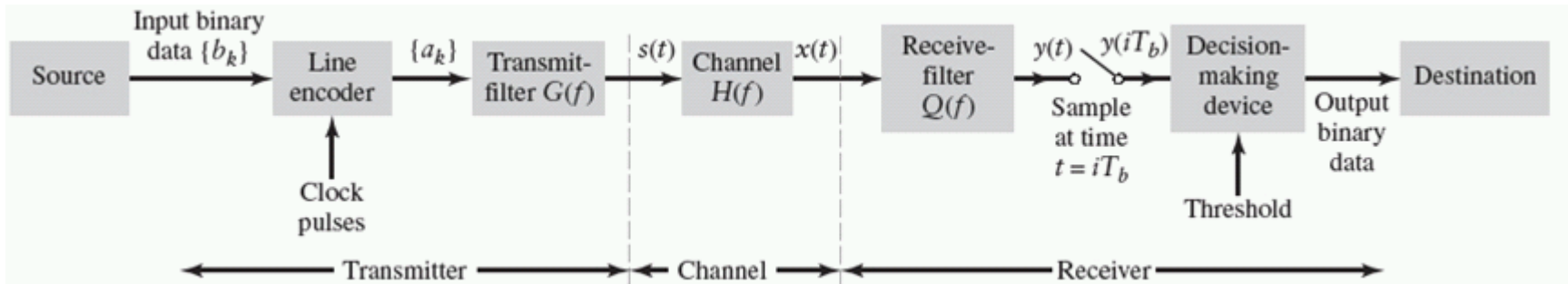
- ❑ Chapter 6: Introduction to Baseband Data Transmission by Pulse Amplitude Modulation (PAM)
 - No modulation, sending pulse sequences directly
 - Suitable for lowpass channels (eg, coaxial cables)
 - The model can be used for band pass modulation systems as well (Digital communication course, e.g., ENSC 428)
- ❑ In this course we will look at
 - Bit Error Rate for on-off PAM systems
 - Bit Error Rate for Bipolar PAM systems

Introduction

- A digital communication system involves the following operations:
 - Usually Analog data is **sampled** and **digitized**.
 - Transmitter: maps the **digital** information to an **analog** signal.
 - Receiver: records the **analog** signal, and recover the **digital** information.

- The system can introduces two kinds of distortions:
- **Channel noise**: due to random and unpredictable physical phenomena.(Chaps. 9 and 10).
- **Intersymbol interference (ISI)**: due to imperfections in the frequency response of the channel.

6.1 Baseband Transmission with PAM



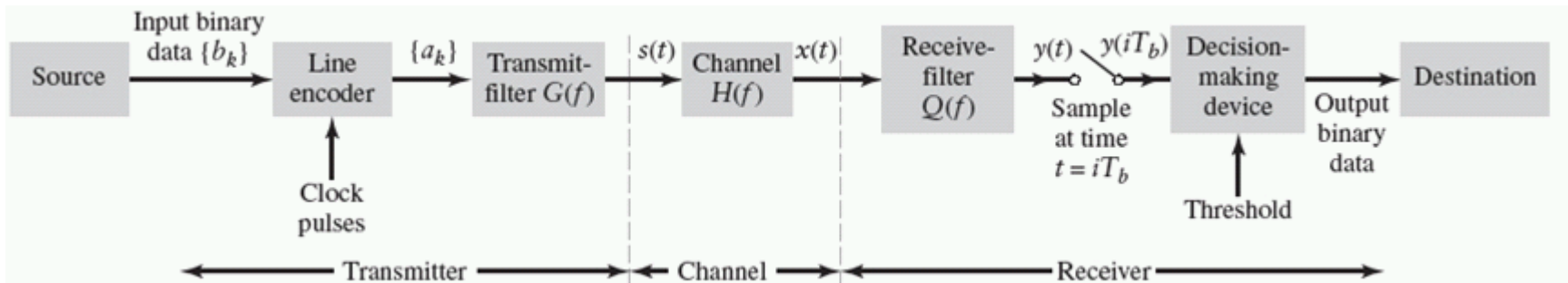
□ **Input:** binary data, $b_k = 0$ or 1 , with duration T_b .

■ Bit rate:

□ **Line encoder:** Electrical representation of the binary sequences, e.g.,

$$a_k = \begin{cases} +1, & b_k = 1, \\ -1, & b_k = 0. \end{cases}$$

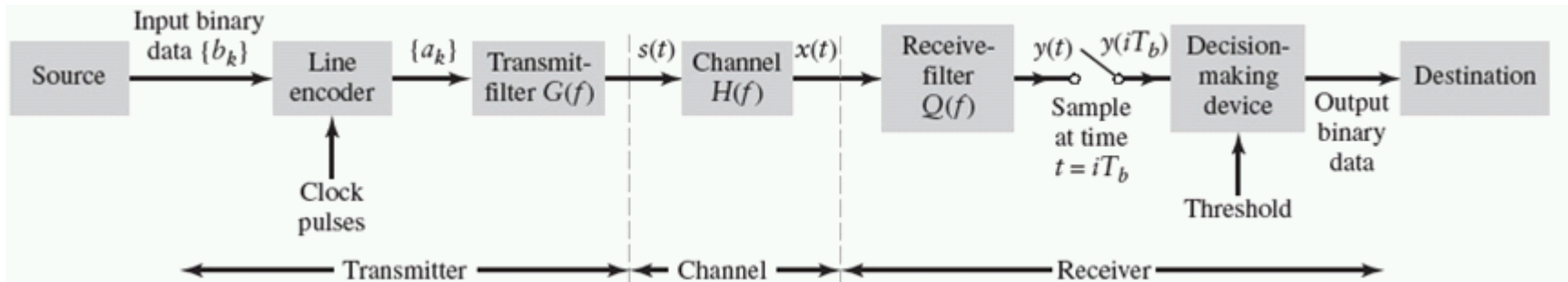
6.1 Baseband Transmission with PAM (Cont.)



- ❑ **Transmit filter:** use pulses of different amplitudes to represent one or more binary bits.
- ❑ The basic shape of the pulse is represented by a filter $g(t)$ or $G(f)$
- ❑ The output PAM signal from the transmitter is then:

$$s(t) = \sum_k a_k g(t - kT_b)$$

6.1 Baseband Transmission with PAM (Cont.)



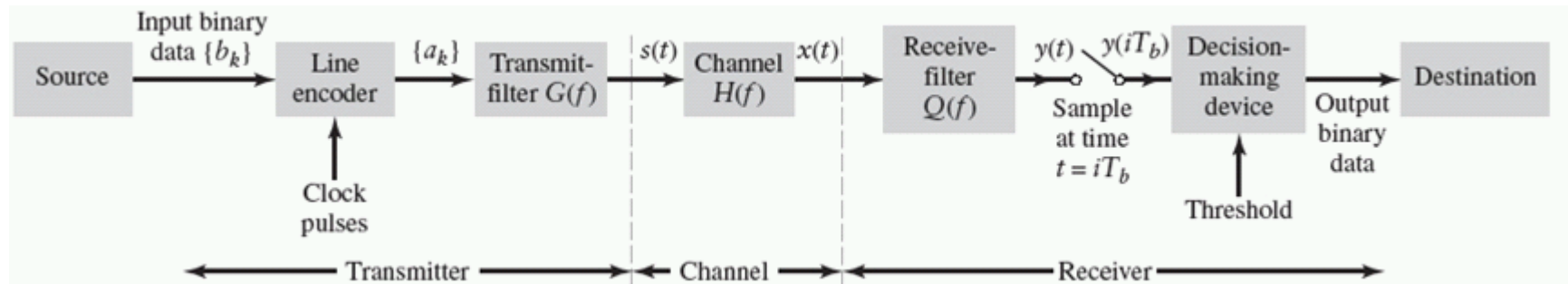
□ Channel:

- If the channel is ideal (ideal all pass filter), no distortion will be introduced.
- Not the case in reality → In practice, a practical channel can be represented by a linear, time invariant (LTI) filter ($H(f)$)

- **The channel output:** the convolution of the transmitted signal and the channel impulse response. This introduces **inter-symbol interference (ISI)**

$$x(t) = s(t) * h(t).$$

6.1 Baseband Transmission with PAM (Cont.)

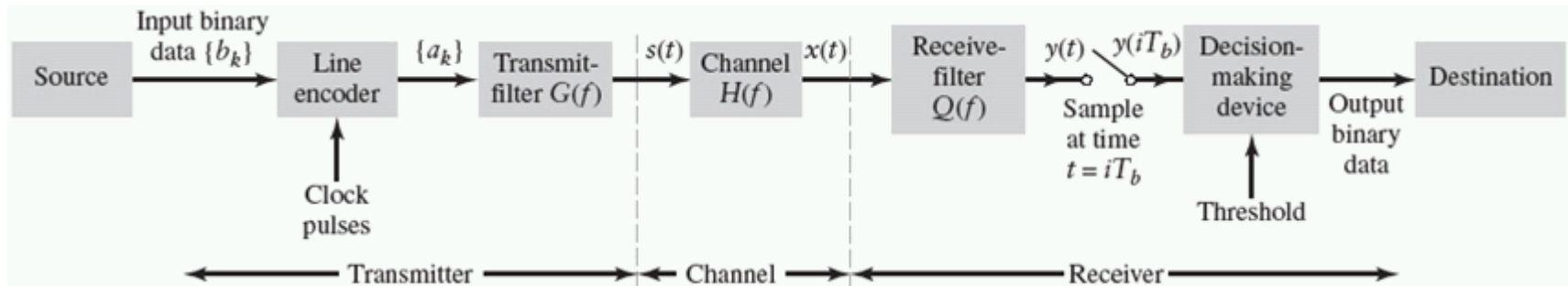


- ❑ **Receiver** can be represented by another filter, aiming to reduce the noise and channel distortion.
- ❑ The output of the receiver filter is:

$$y(t) = x(t) * q(t) = s(t) * h(t) * q(t).$$

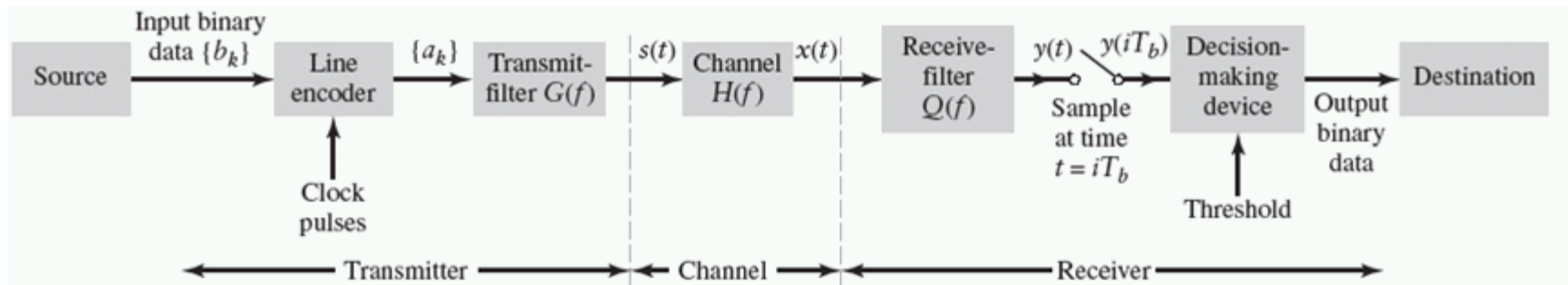
- ❑ The output is then sampled synchronously with the clock at the transmitter.
- ❑ Finally, a decision-making device is used to recover the binary bits. Different methods can be used, e.g.,
 - Threshold, equalization, maximal likelihood decoding

6.1 Baseband Transmission, non-ideal channel



- ❑ The channel's impulse response ($h(t)$ or $H(f)$) is usually not under our control.
- ❑ However the shape of each pulse (determined by filter $g(t)$) and the impulse response of the receiver filter ($q(t)$ or $Q(f)$) can be designed with the following objectives:
 - ❑ The transmitted signal should have a small enough **bandwidth** to meet the bandwidth constraint of the channel.
 - ❑ Given $h(t)$, design $g(t)$ and $q(t)$ to eliminate the inter-symbol interference (**ISI**). (Pulse shaping – We don't cover this subject and assume that the filters are designed such that ISI is eliminated.)

6.1 Baseband Transmission, Ideal Channel



- Assuming an ideal channel, i.e., if the channel acts as an all-pass filter with constant gain (e.g. gain=1), we can have:
 - Ideal rectangular pulses at the transmitter.

 - The ideal receiver (filter + sample and hold) would be an ideal integrator that integrates the received signal over each signaling period ($(k-1)T$ to kT).

- For the rest of this course will make the above simplifying assumptions. 9